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## AMENDMENT TO THE CLAIMS:

Please amend claims 1, 8, 10 and 15 as follows:

1. (Currently amended) A method for processing data to provide a forewarning of a critical event, comprising:

acquiring a plurality of sets of data for a plurality of channels of data for from monitoring at least one physical test subject or physical process;

calculating a set of channel data for a selected parameter from the plurality of channels of data representing parameters that are calculated to provide the selected parameter;

computing a renormalized measure of dissimilarity from distribution functions derived from a phase space for  $\frac{1}{2}$  selected channel of data;

comparing said renormalized measure of dissimilarity to a threshold ( $U_C$ ) for a number of occurrences ( $N_{OCC}$ ) to indicate a condition change in said renormalized measure of dissimilarity; and

detecting a simultaneous condition change in a plurality  $(N_{\text{SIM}})$  of renormalized measures of dissimilarity to determine a forewarning of the critical event; and

providing an output of at least one of a graph, a table of data or an observable signal by which a human observer can detect the forewarning of the critical event.

- 2. (Original) The method of claim 1, wherein the test subject is a human patient.
- 3. (Original) The method of claim 1, wherein the test subject is a mechanical device or physical process.
- 4. (Previously presented) The method of claim 1, wherein the selected parameter is three-phase electrical power.
- 5. (Previously presented) The method of claim 1, wherein the selected parameter is vibration mechanical power.

- 6. (Previously presented) The method of claim 1, wherein the selected parameter is a difference between two channels of EEG data.
- 7. (Original) The method of claim 1, further comprising: performing a first filtering of each set of data with a zero-phase quadratic filter that filters out high-frequency artifacts; and

performing a second filtering of each set of data with a zero-phase quadratic filter to filter out low-frequency artifacts.

8. (Currently amended) The method of claim 1, further comprising:

sorting the data values into ascending order from a minimum to a maximum;

determining the number of unique signal values (n) and the corresponding relative occurrence frequency  $(F_k)$  for each unique signal value  $(v_k)$ ;

displaying a graph of frequency  $(F_k)$  versus values  $(v_k)$  in each bin in a connected phase space; and

discarding data that has  $[v_k - (N/n)]/\sigma_3 > z$ , where the value of z is determined by solving  $1/n = \frac{1}{2} \operatorname{erfc}(z/\sqrt{2})$ , and  $\sigma_3$  is the standard deviation in the occurrence frequency.

9. (Original) The method of claim 1, with an alternative embodiment for event forewarning, comprising determining a sequence of renormalized phase space dissimilarity measures from data sets for the test subject or process; summing said renormalized measures into a composite measure,  $C_i$ , for the i-th data set; performing a least-squares analysis over a window of m points of the said composite measure to obtain a straight line,  $y_i=ai+b$ , that best fits said composite data in a least-squares sense; determining the variance,  $\sigma_1^2 = \sum_i (y_i - C_i)^2/(m-1)$ , of said

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composite measure with respect to the straight line fit; obtaining the variability of the sequel window of m sequential points via the statistic,  $G = \Sigma_i \ (y_i - C_i)^2/\sigma_1^2$ ; comparing said value of G to the running maximum value of the same statistic,  $G_{max}$ ; determining the forewarning of or failure onset of a critical event (such as a machine failure), when G is significantly more than  $G_{max}$ ; obtaining the ratio,  $R = (G_{max})_k/(G_{max})_{k-1}$ , of the present and previous running maximum in G; and determining the forewarning of a critical event when R is significantly more than some limit.

10. (Previously presented) A method for processing data to provide a forewarning of a critical event, comprising:

acquiring a plurality of sets of data for at least two channels of data for from monitoring at least one physical test subject or physical process;

producing a set of multi-channel data representing a combination of said at least two channels of data;

computing a multi-channel time-delay phase-space (PS) construction, which has the form:  $y(i) = [s(1)_i, s(1)_{i+\lambda}, s(1)_{i+\lambda}, s(1)_{i+2\lambda}, \dots, s(2), s(2)_{i+\lambda}, s(2)_{i+2\lambda}, \dots, s(c)_i, s(c)_{i+\lambda}, s(c)_{i+2\lambda}, \dots],$  where s(c) denotes the symbolized data for c-th channel;

computing a renormalized measure of dissimilarity from distribution functions derived from the phase space for the multi-channel data;

comparing said renormalized measure of dissimilarity to a threshold  $(U_C)$  for a number of occurrences  $(N_{OCC})$  to indicate a condition change in said renormalized measure of dissimilarity; and

detecting a simultaneous condition change in a plurality  $(N_{\text{SIM}})$  of renormalized measures of dissimilarity to determine a forewarning of the critical event; and

providing an output of at least one of a graph, a table of data or an observable signal by which a human observer can detect the forewarning of the critical event.

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11. (Original) The method of claim 10, further comprising: performing a first filtering of each set of data with a zero-phase quadratic filter that filters out high-frequency artifacts; and

performing a second filtering of each set of data with a zero-phase quadratic filter to filter out low-frequency artifacts.

- (Original) The method of claim 10, using an alternative embodiment for event forewarning, comprising determining a sequence of renormalized phase space dissimilarity measures from data sets collected during increasingly severe fault conditions; summing said renormalized measures into a composite measure, Ci, for the i-th data set; performing a least-squares analysis over a window of m points of the said composite measure to obtain a straight line,  $y_i=ai+b$ , that best fits said composite data in a least-squares sense; determining the variance,  $\sigma_1^2 = \Sigma_i$   $(y_i - y_i)$  $(C_i)^2/(m-1)$ , of said composite measure with respect to the straight line fit; obtaining the variability of a sequel window of m sequential points via the statistic,  $G = \sum_{i} (y_i - C_i)^2 / \sigma_i^2$ ; comparing said value of G to the running maximum value of the same statistic,  $G_{max}$ ; and determining the onset of a critical event, such as forewarning of a machine failure, when G is significantly more than G(non-end-of-life), or when R significantly more than R(non-end-of-life), or detection of failure onset when G is significantly greater than G(end-oflife).
- 13. (Original) The method of claim 10, wherein the test subject is a human patient.
- 14. (Original) The method of claim 10, wherein the test subject is a mechanical device or physical process.

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15. (Currently amended) The method of claim 10, further comprising:

sorting the data values into ascending order from a minimum to a maximum;

determining the number of unique signal values (n) and the corresponding relative occurrence frequency  $(F_k)$  for each unique signal value  $(v_k)$ ;

displaying a graph of frequency  $(F_k)$  versus values  $(v_k)$  in each bin in a connected phase space; and

discarding data that has  $[v_k - (N/n)]/\sigma_3 > z$ , where the value of z is determined by solving  $1/n = \frac{1}{2} \operatorname{erfc}(z/\sqrt{2})$ , and  $\sigma_3$  is the standard deviation in the occurrence frequency.

- 16. (Previously presented) The method of claim 10, wherein the multi-channel time-delay phase-space (PS) construction is constructed from process-indicative data, which is three-phase electrical power data.
- 17. (Previously presented) The method of claim 10, wherein the multi-channel time-delay phase-space (PS) construction is constructed from process-indicative data, which is vibration mechanical power data.
- 18. (Previously presented) The method of claim 10, wherein the multi-channel time-delay phase-space (PS) construction is constructed from process-indicative data representing a difference between the two channels of data, which is EEG data.